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6 Flow Control based 5 MW Wind Turbine Enhanced 7 Energy Production for Hydrogen Generation Cost 8 Reduction

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19 **Abstract:** Improving the performance and the production of renewable energy sources, especially
20 the wind energy, is considered an attractive approach to reduce the Cost of Energy (COE) associated
21 to the hydrogen generation process. In this context, flow control strategies have been object of
22 detailed investigation during last years. Originally flow control devices were designed to be
23 implemented in the aeronautical sector. Nonetheless, the optimization of the performance of the
24 wind turbine blades with the introduction and implementation of these devices is being widely
25 investigated these days. An analysis of the influence of implementing Vortex Generators (VGs) and
26 Gurney Flaps (GFs) in Wind Turbine Blades (WTBs) on the Annual Energy Production (AEP) of
27 large Horizontal Axis Wind Turbine (HAWT) is proposed in this paper. For that purpose, the
28 Weibull distributions of annual wind speed data series of a real wind farm have been calculated,
29 and Blade Element Momentum (BEM) based calculations have been performed to evaluate the effect
30 of the flow control devices on the power curve and the AEP of the NREL offshore 5 MW Baseline
31 Wind Turbine. The obtained results show an enhancement of the AEP of the turbine of 2.43% during
32 year 2015 and 2.68% during year 2016. As a result, increments of the generated hydrogen volume
33 larger than 130000 Nm³ are achieved during both years with no considerable additional cost in the
34 design of the wind turbine.

35 **Keywords:** Hydrogen Fuel Cell, Cost of Energy, Passive flow control; Vortex Generators; Gurney
36 Flaps; AEP.
37

38 1. Introduction

39 Wind energy and electrical mobility systems are gaining in significance as the renewable energy
40 generation increases due to the necessity of an energetic transition. The environmental pollution and
41 the risk of depletion of the carbon based fuels has derived in an increase in the use of sustainable
42 mobility and energy generation systems. One alternative to the conventional gas/diesel based
43 vehicles are the fuel cells [1,2], in which the electrical energy is obtained through the chemical reaction
44 of some input reactives. The most widely used fuel cell is the hydrogen fuel cell, in which oxygen
45 and hydrogen are combined to produce electrical energy and water as the only by-product. A detailed
46 explanation about the hydrogen as an energy source is given by Momirlana et al. [3].

47 The biggest drawback of the hydrogen fuel cell technology is the electrolysis reaction needed to
48 obtain the input hydrogen. The high carbon emissions if natural gas is used as the energy source of
49 the electrolysis process and the high costs associated to renewable energy sources as input of this
50 reaction have avoided the industrial development of the hydrogen fuel cell technology. Nowadays,
51 in order to reduce carbon emissions to the atmosphere renewable energy sources are intended to
52 generate the energy necessary for the generation of the hydrogen. Autonomous hydrogen production
53 systems based on photovoltaic energy [4], wind energy [5,6] and hybrid photovoltaic and wind
54 energy sources [7] can be found in the literature. The improvement of the performance of the
55 renewable energy generation systems, in this paper the wind energy, is being investigated with the
56 objective of reducing the Cost of the Energy (COE) associated to the hydrogen generation process
57 [8,9].

58 The wind energy rises as one of the most prominent renewable energy sources, being the most
59 productive one, and reaching a degree of maturity that permits to achieve efficiency values between
60 96% and 99%, according to Martinez-Suarez et al. [10]. Despite this high value of efficiency, many
61 research can be found in the literature intended to upgrade the performance of the wind turbines and
62 increase the energetic production of these systems, making, thus, the technology more cost effective.

63 An overview of the literature shows the existence of several solutions ranging from the design
64 of novel software based control strategies to the design and introduction of new hardware elements
65 intended to improve the quality of the generated electrical power or the aerodynamic performance
66 of the wind turbines blades. Terzi et al. [11] and Astolfi et al. [12] investigate the contribution of
67 aerodynamic and control solutions to upgrade the power curve of a multi-megawatt wind turbine.
68 The control of the flow across the Wind Turbine Blades (WTBs) is usually handled by flow control
69 devices due to their excellent features for this task. Consequently, the aerodynamic performance and
70 the energetic production of the system can be considerably enhanced. As stated by Baldacchino et al.
71 [13], the increasing size and rated power of the actual wind turbines result in the increment of the
72 structural and fatigue loads in the blades and the design and construction of thicker blade root
73 sections. This new form of the blades has an undesirable effect on the aerodynamic performance of
74 the blades due to an earlier separation of the boundary layer in the suction side of the mid-outer
75 parts. Over the last years numerous flow control devices have been in detail investigated with the
76 objective of overcoming the problem of the premature separation of the boundary layer. Some of
77 them are reviewed in the work of Johnson et al. [14]. The majority of them were originally conceived
78 for their introduction in the aeronautical sector and, nowadays, their optimization and
79 implementation in the field of the wind energy is being faced [15,16]. The most usual classification of
80 these devices is done according to their operating principle. Active flow control devices and passive
81 flow control devices [17,18]. Unlike the operation of the active flow control devices, which are
82 dependent on an external energy source, passive flow control mechanisms do not need an external
83 excitation and more affordable form the cost point of view. Nevertheless, the performance of the
84 passive flow control devices does not adapt to the state of the flow, but they actuate in a predefined
85 way. Among passive flow control devices Vortex Generators (VGs) and Gurney Flaps (GFs) seem to
86 be two of the most capable passive devices.

87 According to the work of Saenz-Aguirre et al. [19], a VG consists of a small vane placed normal
88 to the surface of the airfoil in the suction side of the WTB. They are usually designed with an
89 inclination angle with respect to the air flow direction. As described in the work of Fernandez-Gamiz
90 et al. [20], VGs are used to modify the boundary layer motion, bringing momentum from the outer
91 flow region into the inner flow region of the wall bounded flow, and, thus, delaying the separation
92 of the flow from the blade surface. The effect of placing VGs in the surface of wind turbine blade has
93 been widely studied in the literature. The most important advantage of the use of VGs is that as a
94 consequence of the delayed boundary layer separation, the lift coefficient and the power production
95 of the wind turbine are increased. Martinez-Suarez et al. [10] present a gain of a 0.54% and 0.67%
96 in the mechanical torque and thrust force with the application of Rod Vortex Generators (RVG) in a
97 NREL/NASA-Ames Phase VI rotor blade. According to Baldacchino et al. [13], an increase of the drag
98 coefficient and the mechanical loads in the WTBs are some of the drawbacks of these flow control

99 devices. Regarding the design of VGs for wind turbine applications, several possibilities have been
100 found in the literature. Lin [21] describes in his review different physical form variants that can adopt
101 VGs, including rectangular, triangular and trapezoidal shapes. A computational model of different
102 VG geometries placed on a flat plate is described by Gutierrez-Amo et al. [22]. Another important
103 concept in the design of VGs is the height of the flow control devices. Fernandez-Gamiz et al. [20]
104 stated in their work that the height of the VGs usually corresponds with the thickness of the boundary
105 layer at the VG position. Gao et al. [23] study the effect of different VG length, height and spacing
106 values on a DU97-W-300 airfoil via CFD simulations. In the work of Boldacchino et al. [13] the
107 sensitivity of the airfoil in its aerodynamic performance and the effect on the loads when various
108 design parameters are applied to the VGs are studied. An improvement of the power output and a
109 reduction of the cyclic fatigue loads due to the use of VGs in a wind turbine is presented by Gebhardt
110 et al. [24].

111 A GF is a vane positioned normal to the upper or lower side of the airfoil close to the trailing
112 edge with a height between 1% and 2% of the airfoil chord length, see Fernandez-Gamiz et al. [25]
113 and Saenz-Aguirre et al. [19]. Wang et al. [26] and Jeffrey et al. [27] present a detailed analysis of the
114 performance, design and application of GFs in different airfoils. Various GF geometries have been
115 studied in the works of van Dam et al. [28] and Chow et al. [29]. Furthermore, according to Shukla et
116 al. [30] the implementation of GFs in NACA0012 and NACA0015 airfoils leads to an improvement in
117 the lift coefficient, the lift force and the velocity of the blades. Storms et al. [31] present in his paper a
118 lift increase of around 13% with negligible drag increment when an adequate sizing of GFs is
119 adopted. Woodgate et al. [32] demonstrate the implementation and use of GFs on Computational
120 Fluid Dynamics (CFD) simulations of blades and rotors. According to Holst et al. [33], the solution of
121 GFs is a feasible candidate for large-scale wind turbine implementation to improve rotor
122 aerodynamic performance and to extend the lifetime of future multi-megawatt wind turbines.

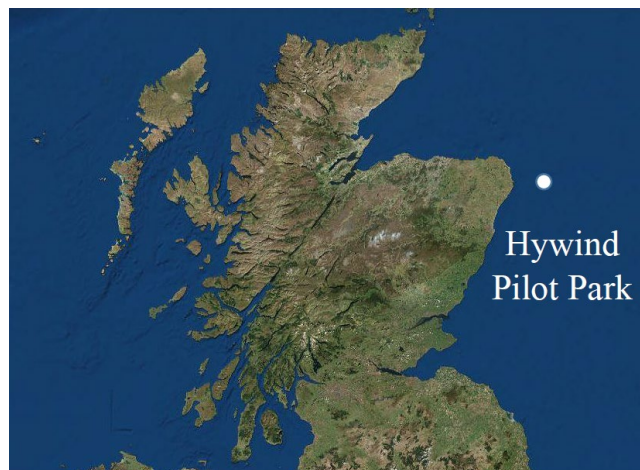
123 The NREL 5MW reference wind turbine of Jonkman et al. [34] is considered the basis of the
124 future offshore Horizontal Axis Wind Turbines (HAWTs). As a result, many investigation and
125 characterization studies about this turbine have been carried out. The WTBs considered in the present
126 work have the same airfoils and chord configuration as the latter introduced NREL 5MW turbine.
127 Timmer et al. [35] give detailed information and wind tunnel data on the airfoils of the DU family
128 that have been considered for the current study.

129 An analysis of the influence of implementing Vortex Generators (VGs) and Gurney Flaps (GFs)
130 in Wind Turbine Blades (WTBs) on the Annual Energy Production (AEP) of a large Horizontal Axis
131 Wind Turbine (HAWT) and the consequent reduction of the COE of the hydrogen generation process
132 for electric mobility applications is proposed in this paper. In fact, this analysis enables to test and
133 quantify the performance and efficiency of flow control strategies, recently introduced in the wind
134 energy sector, to enhance the operation of a HAWT and promote the use of the carbon emission free
135 hydrogen as the key fuel in the future electric mobility infrastructure. For that purpose, the NASA
136 Earth data website [36] has been used as the source of wind speed data of the years 2015 and 2016 in
137 the Hywind Pilot Park wind farm at 3 different heights (2 m, 10 m and 50 m). Extrapolation of this
138 data to the hub height of the NREL 5MW reference wind turbine of Jonkman et al. [34] and
139 calculations based on Blade Element Momentum (BEM) have been performed to analyze the effect of
140 the passive flow control devices in the performance of the wind turbine. Full details of all the
141 experimental polar curves and the wind tunnel experiments at the Low-Speed Tunnel with a
142 Reynolds number of 2×10^6 presented by the TU Delft University for the AVATAR project are given
143 by Timmer et al. [35].

144 The current paper is structured as follows: The location of the hypothetical wind turbine that
145 has been considered in the analysis is presented in section 2. Section 3 conducts the explanations and
146 calculations necessary to characterize the annual wind speed data series in the location in which the
147 wind turbine is to be placed. Section 4 presents the algorithm for the calculation of the power curve
148 of a given wind turbine. Finally, sections 5 and 6 correspond to the current results and conclusions,
149 respectively.

150 2. Wind Turbine Location

151 In this section, the geographical location of the hypothetical wind turbine considered in the
 152 current study is presented. The selected location for the offshore wind turbine is the Hywind Pilot
 153 Park, in the North Sea, close to the coast of Scotland, as shown in Figure 1. The wind turbine model
 154 to be installed is the NREL 5 MW, presented by Jonkman et al. [34], and which has been widely-used
 155 for offshore wind energy applications.
 156



157
 158

Figure 1. Hywind Pilot Park Offshore Wind Farm location

159 Hywind Pilot Park is a wind farm, with an installed power capacity of 30 MW and a cover area
 160 of 15 km². The main characteristics of this wind energy project are listed in Table 1. Hywind Pilot
 161 Park has been selected as the reference location for the analysis carried out in this paper due to the
 162 notorious growth in the development of offshore wind farms. Offshore technology, in comparison
 163 with the onshore technology, presents several important advantages. First, the absence of physical
 164 obstacles in the sea enables the wind turbine to receive stronger winds and consequently increment
 165 its generated power. Moreover, since the temperature of the sea is more stable than the temperature
 166 of the ground turbulences are less common in offshore wind farms, and the lifespan of wind turbines
 167 is increased. Finally, due to the absence of noise restrictions in the sea, the rotor can be programmed
 168 to rotate faster, and a design with less weight is possible, which is translated to a reduction of costs.

169 **Table 1.** Principal characteristics of Hywind Pilot Park wind turbines [37,38]

Designer	Siemens
Wind turbine model	SWT-6.0-154
Number of turbines	5
Wind farm rated power	30 MW
Expected life	20 years

170
 171
 172
 173
 174

Finally, with the objective of obtaining the wind resource data corresponding to the exact location of the wind farm, its geographical coordinates have been extracted.

- Latitude: 57.484°
- Altitude: -1.363°

175 3. Annual Wind Speed Characterization

176 3.1. Wind Speed Data, Roughness and Extrapolation

177 The first step of the analysis carried out in this document is the characterization of the wind
 178 speed at a height corresponding to the hub height of the considered wind turbine during a
 179 determined period of time. As it has already been stated in section 1 of this paper, the NASA Earth
 180 database [36] has been used as the source of the wind speed data corresponding to the location of the

181 analyzed turbine. Three different timespan values are available for the average wind speed bins
 182 stored in this database: 1 hour, 3 hours and 1 month. To the end of making the most accurate possible
 183 calculations, 1 hour averages have been chosen.

184 Wind speed data corresponding to the years 2015 and 2016 have been used to elaborate the wind
 185 speed profile of each one of these years. Since in the NASA Earth data database the wind speeds are
 186 only available at heights of 2 m, 10 m and 50 m, an extrapolation of these data to the hub height of 90
 187 m, which corresponds to the hub height of the NREL 5MW turbine, is necessary. Principal
 188 characteristics of the NREL 5MW wind turbine are presented in section 4 of this document. One
 189 important factor to be considered when extrapolating wind speed data is the roughness of the earth
 190 surface. As it is exposed by Wan et al. [39], the roughness of the earth has a considerable influence on
 191 the speed of the wind in the lowest part of the atmosphere, which is commonly known as the
 192 Atmospheric Boundary Layer (ABL). The ABL is defined as the range of elevation in which wind
 193 speeds are affected by the Earth's surface, creating turbulence. As a result, the location of a wind
 194 turbine is a vital parameter when maximizing the wind speed values that are received by the
 195 generation system. The effect of ABL scenarios in the wake left by a wind turbine is studied in the
 196 work of Kabir et al. [40].

197 In the wind energy industry, the roughness is evaluated in meters (m) and refers to the
 198 equivalent height at which the horizontal mean wind speed value theoretically takes the value zero.
 199 Even if it is not a physical length, it is considered as an evaluation of the roughness of the surface and
 200 the wind conditions in a determined geographical location. The value of this parameter is in direct
 201 relation with the height of the elements present in the area analyzed, e.g. the value of the roughness
 202 is larger for cities with high buildings than for a flat area with no trees or buildings. Different values
 203 of the roughness length with respect to various geographical locations are listed in the work of
 204 Bañuelos-Ruedas et al [41].

205 Another concept related to the roughness of the earth surface is the wind shear, which is also
 206 known as the wind gradient and refers to the vertical gradient of the mean horizontal wind speed in
 207 the ABL. According to Hadi [42], the surface friction forces, which are generated by the roughness of
 208 the earth surface, slow down the wind, and a vertical gradient for the wind speed appears as a result.
 209 The bigger the value of the roughness is, the taller the wind shear will be. Empirical values of the
 210 wind shear coefficient with respect to the roughness of the terrain are presented in Table 2.

211 **Table 2.** Empirical wind shear coefficient values [39]

Terrain	Wind shear exponent
Smooth (Sea, snow, sand,)	0.10 - 0.13
Medium irregularities (Villages, farmland)	0.13 - 0.20
Irregularities (Suburbs, forests)	0.20 - 0.27
High irregularities (Tall buildings, cities)	0.27 - 0.40

212
 213 The main objective of the analysis developed in this subsection is to obtain an average wind
 214 speed profile at the hub height of the analyzed NREL 5MW wind turbine. Once the wind speed
 215 profile in the location of the turbine is calculated, the AEP of the generator will be computed. The
 216 process of calculating wind speed values at a determined height starting from wind speed values at
 217 a different height is known as extrapolation.

218 As previously highlighted, the impact of the geographical surroundings of the wind turbine on
 219 the wind speed needs to be considered in order to extrapolate with the highest accuracy.
 220 Consequently, the roughness length has to be taken into account in the calculations. For the case of
 221 offshore wind farms, which is the case of the present study, the reduced roughness over water, and
 222 consequent small wind gradient, means that the extrapolation process should not be very affected by
 223 the surface roughness.

224 The performance of two different extrapolation methods, Logarithmic wind profile law and
 225 Hellman exponential law or power law, has been analyzed and compared. Thus, the one with the
 226 best performance is used for the calculations during the analysis carried out in this paper. A

227 comparison between these both extrapolation techniques applied to offshore wind energy
 228 applications can be found in Emeis et al. [43].

229 On one hand, the mathematical expression corresponding to the Logarithmic wind profile law
 230 is given in Eq. (1).

$$231 \quad \frac{v}{v_0} = \frac{\ln\left(\frac{H}{z_0}\right)}{\ln\left(\frac{H_0}{z_0}\right)} \quad (1)$$

232 where H_0 is the reference altitude, H is the altitude at which wind speed will be extrapolated,
 233 v_0 is the reference wind speed, v is the wind speed to be calculated and z_0 is the roughness length.

234 On the other hand, the mathematical expression corresponding to the Hellman exponential law
 235 or power law is given in Eq. (2).

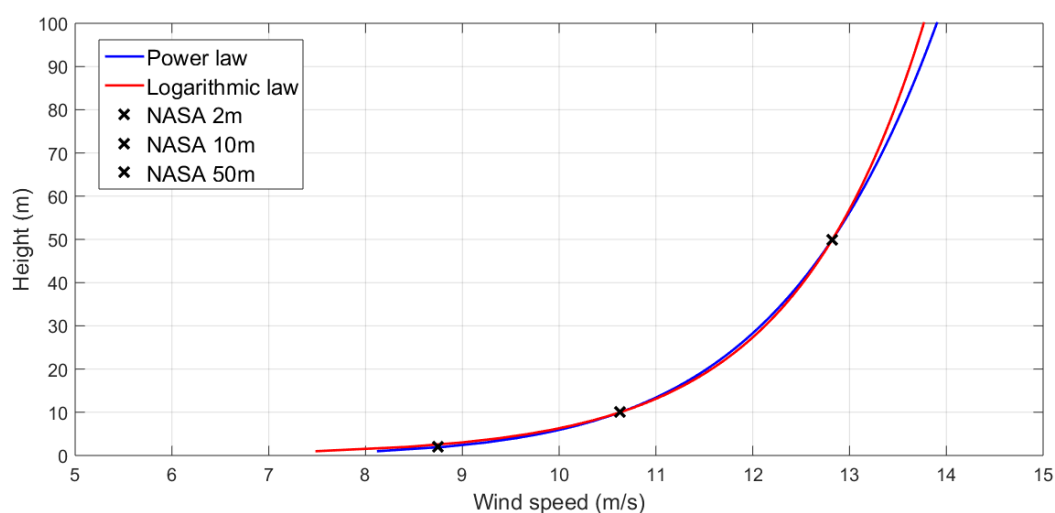
$$236 \quad \frac{v}{v_0} = \left(\frac{H}{H_0}\right)^\alpha \quad (2)$$

237 where H_0 is the reference altitude, H is the altitude at which wind speed will be extrapolated,
 238 v_0 is the reference wind speed, v is the wind speed to be calculated and α is the Hellman or friction
 239 coefficient.

240 According to the analysis carried out by Bañuelos-Ruedas et al [41] by comparing the
 241 performance of the two extrapolations methods, both are considered to give similar results in cases
 242 of not high altitudes, i.e., up to 50 m, in neutral atmospheric conditions. For altitudes higher than 50
 243 m, the results of both methods start to differ, and, according to Hadi [42], the Hellman exponential
 244 law is considered to have a better performance.

245 In the present case, the wind speed values available in the NASA database, at 2 m, 10 m and 50
 246 m high, are used. Consequently, wind speed values at 10m are considered as a reference, and wind
 247 speed values at 50 m are estimated with the previous exposed both extrapolation techniques,
 248 comparing the obtained results.

249 According to the values presented in Figure 2, the extrapolation process is observed to be, as
 250 expected, very similar and accurate with the both analyzed extrapolations methods for heights up to
 251 50 m. For higher values of the height the extrapolation results start to differ from to the other.
 252 Consequently, since the hub height value of 90 m is closer to 100 m than to 20 m., for further analysis
 253 in this paper, the Hellman exponential law technique is to be used to extrapolate wind data values to
 254 the hub height of the NREL 5MW wind turbine.
 255



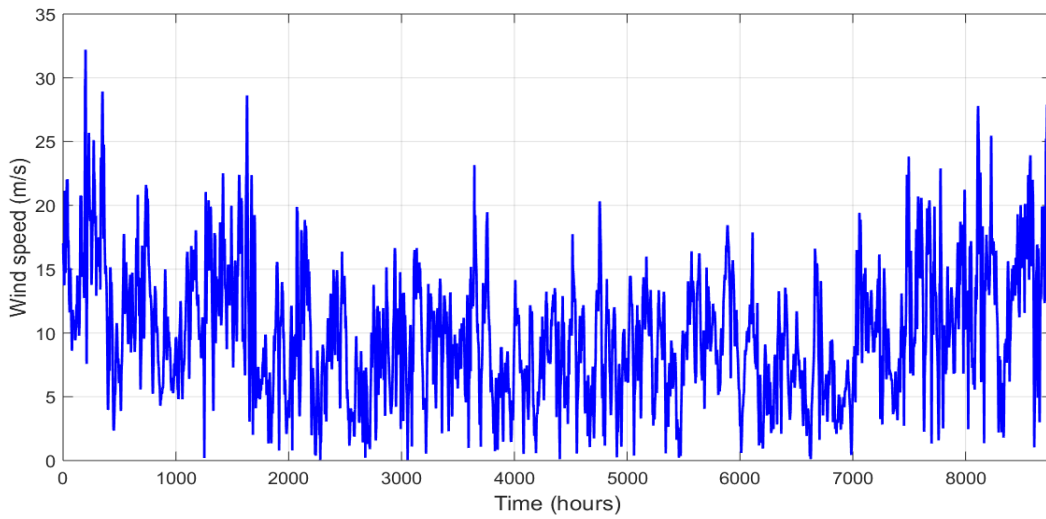
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Figure 2. Comparison between analyzed extrapolation techniques

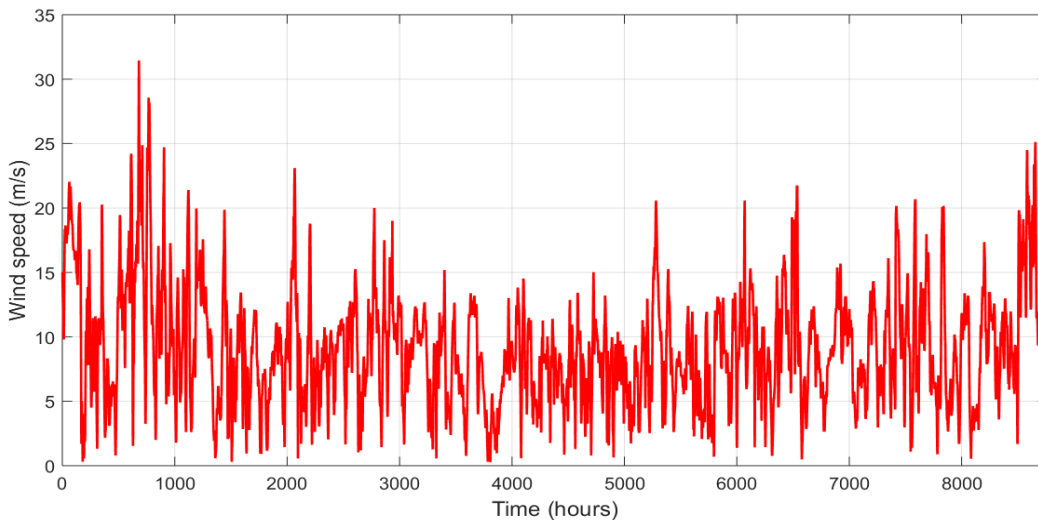
258 Annual wind speed profiles of the years 2015 and 2016, at 90 m of altitude, in the Hywind Pilot
 259 Park wind farm, are represented in Figure 3 and Figure 4, respectively. These wind speed data have

260 been correlated with the Hellmann exponential law, see Eq. (2), with the friction coefficient set to
 261 $\alpha = 0.116479$, which is calculated from the relation of the already known values of the wind speed
 262 at heights of 10m and 50m.
 263



264
 265

Figure 3. Profile of the wind speed in the year 2015



266
 267

Figure 4. Profile of the wind speed in the year 2016

268 *3.2. Wind Speed Distribution*

269 According to Gugliani et al. [44] and Aghbalou et al. [45], the description of the wind speeds in
 270 a determined location is of great significance, since an accurate description of this probability function
 271 can derive in an optimal design of the wind turbines and a better estimation of the electrical energy
 272 generated by a wind turbine or a wind farm. In probability theory and statistics, the Weibull
 273 distribution is a continuous description of a random phenomenon in terms of the probability of
 274 events. In the wind energy field, the Weibull distribution describes the probability of a determined
 275 wind speed value to be observed in the location of a wind turbine. The sample space is formed by the
 276 wind speed value range in that particular location.

277 The function that describes the relative likelihood by which the value of the random variable
 278 would equal the value of the sample is the Probability Density Function (PDF). This PDF is used to
 279 specify the probability of the random variable to fall within a particular range of values, and to
 280 graphically illustrate the Weibull diagram. The PDF of a Weibull distribution is given by Eq. (3).

281

$$f(x) = \frac{k}{c} \cdot \left(\frac{x}{c}\right)^{k-1} e^{-\left(\frac{x}{c}\right)^k} \tag{3}$$

282

where k and c are the shape and scale parameter, respectively.

283

The shape parameter is a unitless number and the scale parameter is expressed in the same unit as the given sample variable. The Weibull distribution depends on the value of these two parameters. In case the shape parameter is equal to $k = 2$, the distribution is also known as the Rayleigh distribution and is frequently used by wind turbine manufacturers to estimate the energy output of wind turbines. Different methods to calculate the parameters of a Weibull distribution can be found in the scientific literature; see Mohammadi et al. [46] and Saleh et al.[47]. In this case, to form a Rayleigh distribution, the shape parameter has been set to $k = 2$ and the scale parameter c has been calculated following the moments method explained in the work of Dorvlo et al. [48], see Eq. (4).

291

$$c = \frac{\bar{v}}{\Gamma\left(1+\frac{1}{k}\right)} \tag{4}$$

292

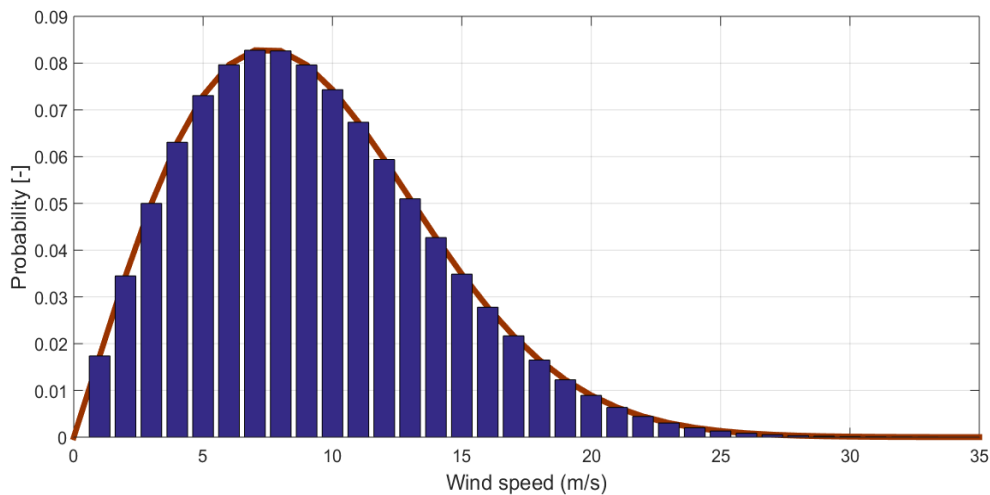
The Weibull distributions of the annual wind speed data, at 90 m of altitude and in the Hywind Pilot Park wind farm, are illustrated for the years 2015 and 2016 in Figure 5 and Figure 6, respectively. The considered shape and scale parameters are $k = 2$ and $c = 11.18 \text{ m/s}$ for the 2015 year distribution, and $k = 2$ and $c = 10.305 \text{ m/s}$ for the 2016 year distribution.

293

294

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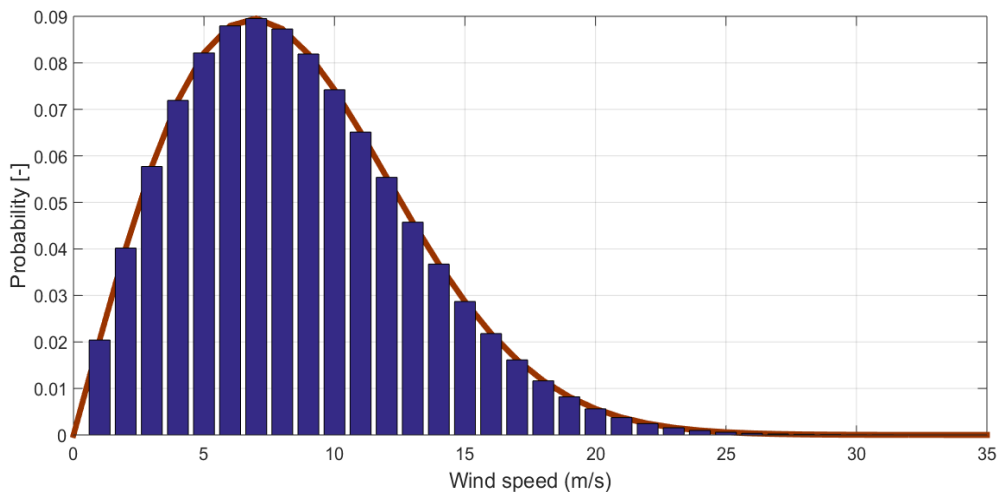
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298

Figure 5. Weibull distribution diagram of 2015 wind speeds



299

300

Figure 6. Weibull distribution diagram of 2016 wind speeds

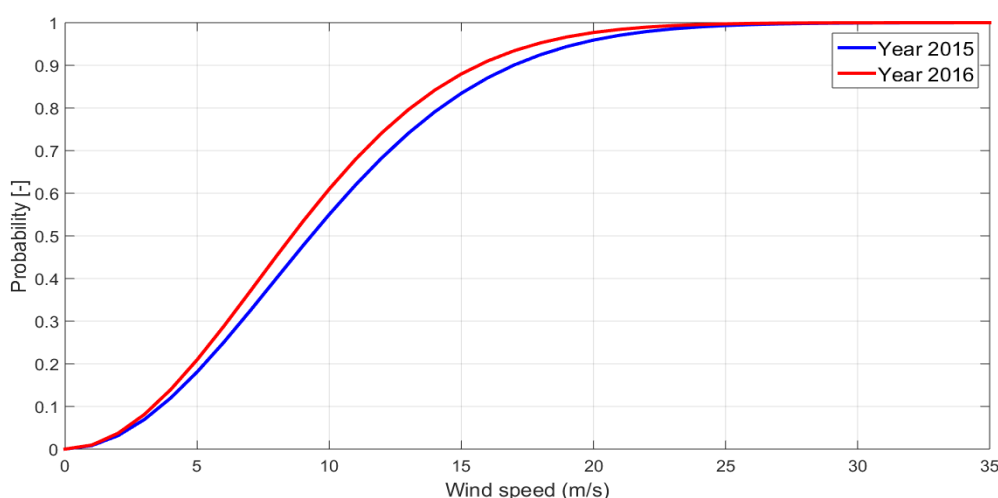
301 Another diagram that is used to illustrate the distribution of a series of data is the Cumulative
 302 Weibull distribution, explained by Faghani et al. [49] and given by Eq. (5).

303
$$f(x) = 1 - e^{-\left(\frac{x}{c}\right)^k} \tag{5}$$

304 The Cumulative Weibull distribution is related to the conventional Weibull distribution, but it
 305 allows to observe the distribution of the wind data series form a different perspective. The sample
 306 space is set to the wind speed range in that particular location and, for the last value of this range,
 307 the unity value is reached in the cumulative function. The cumulative function must be integrated
 308 between the two edge values of the range in order to calculate the probability of a wind value range
 309 to be observed in the location of the wind turbine.

310 The Cumulative Weibull distributions of the annual wind speed data corresponding to the years
 311 2015 and 2016, extrapolated at 90 m of altitude, and located in the Hywind Pilot Park, are illustrated
 312 in Figure 7.

313



314

315

Figure 7. Cumulative Weibull distribution diagram of 2015 and 2016 wind speeds

316 **4. Wind Turbine Performance**

317 In this section, the performance of the wind turbine related to its aerodynamic behavior is
 318 analyzed. To that end the performance of a clean turbine, i.e., a turbine without any flow control
 319 device implemented on the blades, is compared with the performance of a turbine with passive flow
 320 control devices (VGs and GFs) by computation of its power curve. Jonkman et al. [34] described the
 321 characteristics of the NREL 5MW wind turbine, which is used as the reference turbine in the analysis
 322 performed in the current study. The principal characteristics of the NREL reference wind turbine are
 323 summarized in Table 3.

324

Table 3. Principal characteristics of the NREL 5W wind turbines

Turbine model	NREL 5W
Rated power	5 MW
Rotor diameter	126 m
Hub height	90 m
Cut-in wind speed	3 m/s
Rated wind speed	11.4 m/s
Cut-out wind speed	25 m/s

325

326 According to the work of Jonkman et al. [34], the blades of the NREL 5MW turbine are formed
 327 by 17 different stations, each one with its corresponding airfoil shape. The correspondence between
 328 the stations and the airfoils in the blades of the studied turbine is listed in Table 4.

329 **Table 4.** Distribution of the airfoils in the WTBs of the NREL 5MW wind turbine described in [34]

Station number	r (m)	Airfoil Type
1	2.8667	Cylinder1
2	5.6000	Cylinder1
3	8.3333	Cylinder2
4	11.7500	DU40
5	15.8500	DU35
6	19.9500	DU35
7	24.0500	DU97W300
8	28.1500	DU91W(2)250
9	32.2500	DU91W(2)250
10	36.3500	DU93W210
11	40.4500	DU93W210
12	44.5500	NACA64XX
13	48.6500	NACA64XX
14	52.7500	NACA64XX
15	56.1667	NACA64XX
16	58.9000	NACA64XX
17	61.6333	NACA64XX

330 The performance of a wind turbine can be calculated via different methods. Beyhaghi et al. [50]
 331 and Peng et al. [51] carried out CFD analysis to study the aerodynamic performance of a wind turbine.
 332 A computationally more economical and faster method to calculate the power curve of a wind turbine
 333 is the so-called BEM, see Hansen et al. [52]. In the analysis carried out in the present work, the power
 334 curve of the wind turbine is calculated using the BEM method presented in Fernandez-Gamiz et al.
 335 [20]. BEM based calculations have the principal advantage that they are computationally economical
 336 and fast.

337 The basic idea of the BEM method is the calculation of the contribution to the total of each one
 338 of the sections, independent and individually, and its posterior sum to obtain the total value of the
 339 forces generated in the WTB. In order to obtain feasible results, accurate airfoil data of the lift, drag
 340 and moment coefficients of the WTBs must be known.

341 According to the work of Fernandez-Gamiz et al. [20], the performance of the BEM method can
 342 be resumed with the following points:

- 343
- 344 - Initialization of axial and tangential induction parameters, a and a' .
 - 345 - Calculation of the flow angle Φ .
 - 346 - Calculation of the angle of attack α .
 - 347 - Calculation of the lift and drag coefficients, C_L and C_D .
 - 348 - Computation of the normal and tangential load coefficients, C_n and C_t .
 - 349 - Recalculation of the axial and tangential induction parameters, a and a' .
 - 350 - Evaluate the tolerance for axial and induction parameters.
 - 351 - Computation of the power, Eq. (6), thrust, Eq. (7) and bending moment, Eq. (8).

352
$$P = \int_{i=0}^R 4\pi \cdot r_i^3 \cdot \rho \cdot V_0 \cdot w^2 \cdot a'_i \cdot (1 - a_i) \cdot F \cdot dr_i \quad (6)$$

353
$$T = \int_{i=0}^R 4\pi \cdot r_i \cdot \rho \cdot (V_0)^2 \cdot w \cdot a_i \cdot (1 - a_i) \cdot F \cdot dr_i \quad (7)$$

354
$$BM = \int_{i=0}^R 4\pi \cdot r_i^2 \cdot \rho \cdot (V_0)^2 \cdot w \cdot a_i \cdot (1 - a_i) \cdot F \cdot dr_i \quad (8)$$

355 where ρ is the density of the air, V_0 is the wind speed, w is the rotational speed of the wind
 356 turbine and F is the Prandtl's tip loss correction factor.

357 In the BEM algorithm, the working point of each station is assessed in order to calculate its
 358 torque contribution to the total torque developed by the WTB. To calculate these working points, an
 359 iterative algorithm is usually applied. The stop condition can be given by the maximum number of
 360 iterations or by a tolerance in the changes of the values.

361 In this analysis two different scenarios have been considered: A clean wind turbine, i.e. without
 362 any passive flow control device placed on the surface of the blades, and a wind turbine with flow
 363 control devices implemented on the surface of its blades.

364 For the first scenario, corresponding to the clean wind turbine, accurate data of the lift, drag and
 365 moment coefficients of the WTBs have been taken from the experimental work of Timmer et al. [35].
 366 With these data BEM calculations have been performed and the value of the thrust, bending moment,
 367 power coefficient C_p and the power curve have been obtained for the whole range of wind speed
 368 values considered for the operation of the NREL 5MW wind turbine.

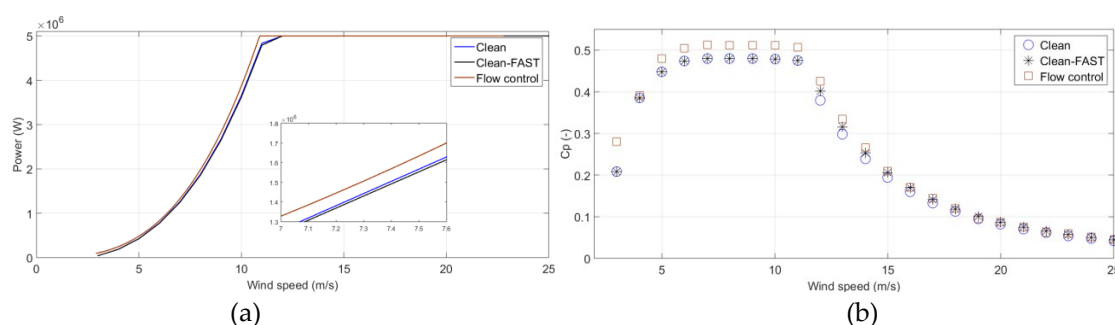
369 For the second scenario, corresponding to wind turbine with flow control devices, CFD
 370 simulations have been carried out to obtain the data of the lift, drag and moment coefficients of the
 371 WTBs. With these data BEM calculations have been performed and the value of the thrust, bending
 372 moment, power coefficient C_p and the power curve have been obtained for the whole range of the
 373 wind speed values considered for the operation of this wind turbine. As a result, an analysis of the
 374 performance of the passive flow control solution independent from the wind speed value can be
 375 carried out.

376 The proposed passive flow control based solution is based on a combination of VGs and GFs
 377 placed on the surface of the blades of the wind turbine, and can be described as follows:

- 378 - In the blade station 7, see Table 4, VGs have been installed in a distance of 30% of the chord
 379 length measured from the leading edge of the airfoil. No GFs have been installed in this
 380 station.
- 381 - In stations 8 and 9 VGs have been installed in a distance of 20% of the chord length measured
 382 from the leading edge of the airfoil. Moreover, GFs with a height of 2% of the chord length
 383 have been installed in the airfoil trailing edge.
- 384 - In blade stations 10 and 11, VGs have been installed in a distance of 60% of the chord length
 385 measured from the leading edge of the airfoil. No GFs have been installed in this stations.

386 This configuration, defined as ID25 in the work of Fernandez-Gamiz et al. [20], has been found
 387 to be the best one (as it maximizes the power coefficient C_p of the wind turbine) from a collection of
 388 25 different possible configurations of these flow control devices applied in the WTBs.

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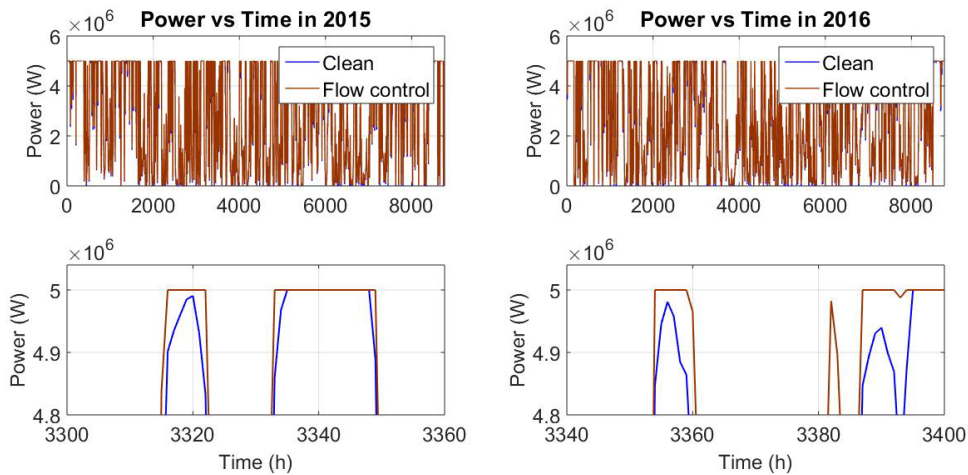
392 **Figure 8.** NREL 5MW wind turbine characteristics. (a) Power curve and (b) C_p power coefficient

393

comparison with and without implementation of passive flow control devices.

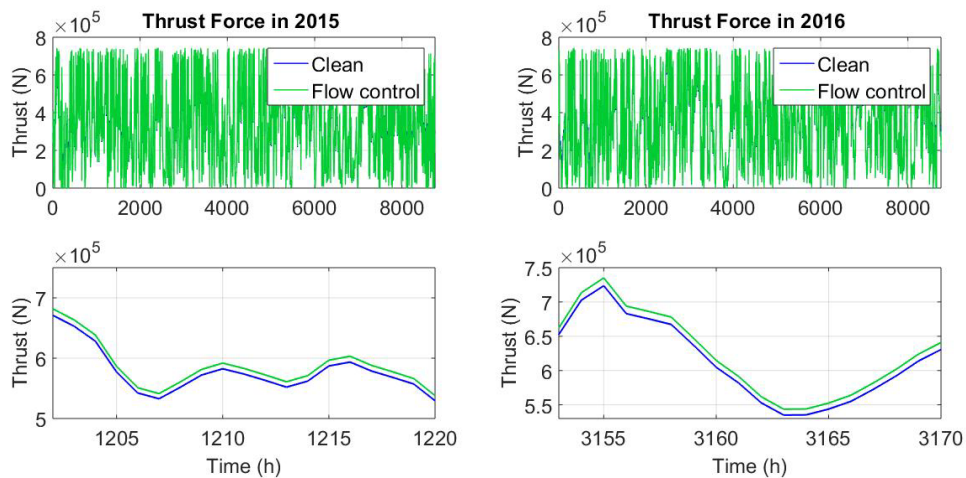
394 Figure 8 represents the results of the BEM calculations based on Fernandez-Gamiz et al. [20].
 395 Figure 8(a) depicts the power curves of the wind turbine with and without passive flow control
 396 devices placed in its blades. The power coefficient C_p has also been computed in Figure 8(b) for
 397 the cases of the clean wind turbine and the case of the wind turbine with the flow control. The curve
 398 of the wind turbine with the devices for flow control follows the tendency of the clean wind turbine

399 curve. Nevertheless, at the wind speeds before the rated power of 5MW, the power output is
 400 enhanced due to the implementation of the flow control devices. As shown in the detailed view
 401 embedded in Figure 8(a), an increase of the power output of the wind turbine in the operating zone
 402 of partial power has been achieved by mounting passive flow control devices in the WTBs. In the
 403 rated power zone, as a result of the control system implemented in the wind turbine, the value of the
 404 generated power is kept to its rated value and the effect of the flow control devices in terms of power
 405 generation becomes negligible. The improvement of the C_p is observed in Figure 8(b) in comparison
 406 with the clean case. The power output and power coefficients of the wind turbine calculated by
 407 Jonkman et al. [34] for the same turbine have also been added in the Figure 8. The power output along
 408 the years 2015 and 2016 is illustrated in Figure 9. A clear increase in the power curve of the wind
 409 turbine with flow control devices is visible compared to the clean wind turbine at both years 2015
 410 and 2016.
 411



412
 413 **Figure 9.** Power generation comparison with and without application of passive flow control
 414 devices.

415 In addition, in order to better characterize the effect of the passive flow control devices on the
 416 performance of the wind turbine, comparative representations of the thrust force and the bending
 417 moment in the root of the blade have been illustrated in Figure 10 and Figure 11, respectively.
 418



419
 420 **Figure 10.** Thrust force comparison with and without application of passive flow control devices

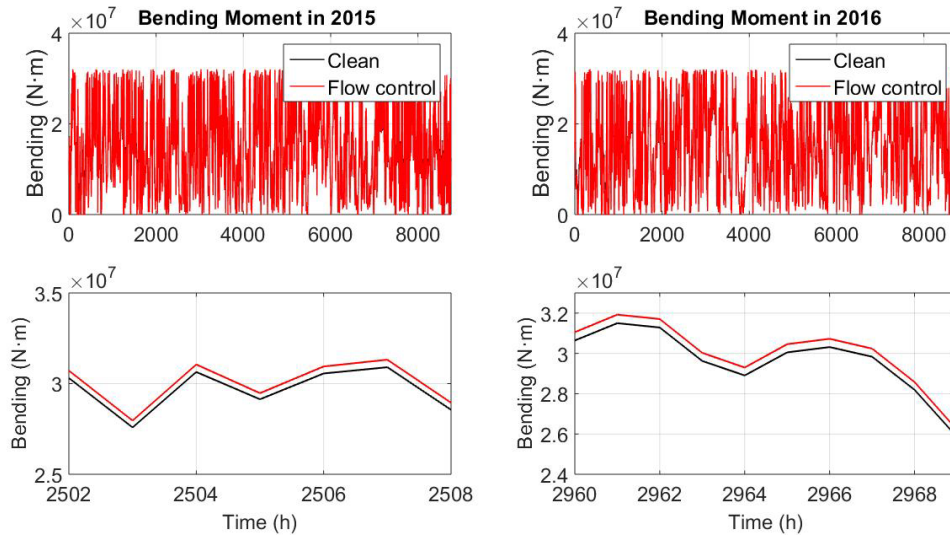


Figure 11. Bending moment comparison with and without application of passive flow control devices

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As expected, the results of Figure 10 and Figure 11 show an increase of the bending moment on the root of the blade and the thrust force of the rotor of the wind turbine for wind speed values below rated (see zoomed views of Figure 10 and Figure 11) with the application of the flow control based solution into the WTBs.

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5. Wind Turbine Annual Energy Production

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In this section, the AEP value of a clean turbine is calculated and compared with the AEP value of a turbine equipped with VGs and GFs in its airfoils, i.e., the effect of placing passive flow control devices on the AEP of a NREL 5 MW turbine is analyzed.

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432

In order to compute AEP value of the wind turbine, the Weibull distribution of the annual wind speed data and the power curve of the turbine have been first obtained in sections 3 and 4. Using these two functions, the AEP of the wind turbine can be easily computed with the expressions given in Eq. (9)-(10).

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$$P_{average} = \frac{\sum_{j=1}^{j=Nbins} P(V_{0,j}) \cdot N(V_{0,j})}{\sum_{j=1}^{j=Nbins} N(V_{0,j})} \quad (W) \quad (9)$$

438

$$AEP = P_{average} \cdot 8760 \quad (W \cdot h) \quad (10)$$

439

$N(V_{0,j})$ represents the number of samples for each bin, V_0 the wind speed and 8760 is the number of hours per year. If the calculation given in Eq. (9) is performed, the mean power of the NREL 5MW wind turbine is calculated using its power curve and the probability function of the wind speed in its location. If the mean power value is multiplied by the number of hours in a whole year, see Eq. (10), the AEP value for that year is obtained. Using the AEP value of the clean NREL 5MW wind turbine as a reference, the increment or decrement of the AEP value of the NREL 5MW wind turbine equipped with the passive flow control devices can be calculated.

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One important aspect regarding VGs and GFs is their facility to be mounted on the blades, as they can be placed on them after the blade is already fabricated, which means that no interference is necessary with the usual fabrication process of the blades.

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453 **Table 5.** Annual Energy Production increase with the application of passive flow control devices

ANNUAL ENERGY PRODUCTION			
Year	Clean (kW·h)	Flow control (kW·h)	Δ AEP (%)
2015	$2.4708 \cdot 10^7$	$2.5309 \cdot 10^7$	2.4329
2016	$2.4371 \cdot 10^7$	$2.5023 \cdot 10^7$	2.6773

454

455 According to the results, presented in Table 5 , the AEP of the NREL 5MW wind turbine
 456 equipped with the VGs and the GFs is incremented by a 2.43% in year 2015 and a 2.68% in year 2016
 457 in comparison to the same wind turbine without these flow control devices located in the Hywind
 458 Pilot Park wind farm. The bigger AEP increase in the case of year 2016 in comparison to year 2015
 459 can be explained with a higher probability of wind speed values above the rated one during year
 460 2015. During these high wind speed intervals the control system of the wind turbine keeps the value
 461 of the generated power to its rated value and the effect of the passive flow control devices disappears.
 462 This can be confirmed with the Weibull distributions shown in Figure 5 and Figure 6. In both cases
 463 the power enhancement is bigger than the one presented by Ebrahimi et al. [53] with the utilization
 464 of plasma actuators in the same wind turbine. In that case the power increase is limited to 0.85% in
 465 the best case.

466

467 If it is considered that the wind farm is connected to the grid, the obtained AEP increment with
 468 the utilization of VGs and GFs can be transformed to economical profits in order to better evaluate
 469 the impact of implementing these passive flow control devices on an offshore wind turbine. Due to
 470 oscillations in the price of the energy in the regulated market, two different prices are considered in
 471 this analysis (3 ct/KW·h and 5 ct/KW·h), as it is also considered in the work of Schramm et al. [54].
 472 Table 6 shows the results in terms of the economical profits for those different scenarios at the years

473 **Table 6.** Annual economical profit with application of passive flow control devices

Economical profit (€)		
Year	3 ct/kW·h	5 ct/kW·h
2015	18030 €	30050 €
2016	19575 €	32625 €

474

475 In the same way, if it is considered that the wind farm is not connected to the grid, but it
 476 corresponds to a Power to Gas plant, i.e. its objective is the large-scale production of hydrogen by
 477 electrolysis, the obtained AEP increment with the utilization of VGs and GFs can be transformed to
 478 a generated additional hydrogen volume. For these calculations, the technical characteristics of the
 479 commercial large-scale electrolyser *McLyzer 400-30* designed by the company *McPhy* and installed in
 480 a 4 MW Power to Gas wind farm [55] in Hebei, China has been considered. The energy consumption
 481 of this electrolyser is 4.5 kW·h/Nm³. The obtained results in terms of annual generated hydrogen
 482 volume are presented in Table 7. The second column shows the volume of hydrogen, in normal
 483 conditions of this gas, generated by the wind farm in each one of the analyzed years with no passive
 484 flow control devices implemented in the WTBs. The third column shows the volume of hydrogen, in
 485 normal conditions of this gas, generated by the wind farm in each one of the analyzed years with
 486 VGs and GFs implemented in the WTBs. The last column corresponds to the generated additional
 487 hydrogen volume with the implementation of the passive flow control devices based solution.

488 **Table 7.** Annual generated hydrogen volume increase with the application of passive flow control
489 devices

ANNUAL HYDROGEN GENERATION			
Year	Clean (Nm ³)	Flow control (Nm ³)	Δ VH ₂ (Nm ³)
2015	$5.4907 \cdot 10^6$	$5.6242 \cdot 10^6$	133500
2016	$5.4158 \cdot 10^6$	$5.5607 \cdot 10^6$	144998

490

491 The annual economical profits and the annual generated additional hydrogen volume in Table
492 6 and Table 7, respectively, indicate the relevancy of implementing passive flow control devices in
493 the blades of a wind turbine. On the one hand, if the wind farm is connected to the grid, with possible
494 annual economical profits of around 30.000 € the time necessary to compensate the initial inversion
495 for the installation of a wind turbine or a wind farm can be reduced, and, hence, the time to start
496 making benefits and the COE are reduced, which is a considered to be a key factor for the promotion
497 of the renewable energies. On the other hand, if the wind farm is a Power to Gas plant, the generated
498 additional hydrogen volume is increased by around 150000 Nm³ with no considerable variation in
499 the price of the wind farm. This additional hydrogen could cover a journey of 100 km of almost 1
500 million of hydrogen cars without extra cost. Hence, a reduction of the associated COE and a
501 significant progress of the hydrogen generation process are to be achieved.

502 6. Conclusions

503 The effect of implementing passive flow control devices, VGs and GFs, on the AEP of a multi
504 megawatt HAWT has been analyzed in this paper. The Weibull distributions of the annual wind
505 speed data corresponding to a real offshore wind farm for two different years have been calculated
506 and BEM based computations have been performed to obtain the power curve of a reference wind
507 turbine model in different scenarios and study the influence of mounting VGs and GFs on the
508 performance of the turbine.

509 According to the obtained results:

- 510 • In the selected location of the wind turbine, an increment of 2.43% and 2.68% is achieved
511 in the AEP of the turbine in the years 2015 and 2016, respectively, with the introduction
512 of the flow control devices.
- 513 • These increments of 2.46% and 2.68% can be transformed to economical profits of 30050
514 € and 46900 € or generated additional hydrogen volumes of 133500Nm³ and 208400 Nm³
515 for each one of the analyzed years.
- 516 • The economical profits permit to reduce the time necessary to compensate the initial
517 inversion and start making benefits. The generated additional hydrogen volume enable
518 to increase the efficiency of the hydrogen generation process. Either way an important
519 reduction of the COE associated to the energy generation process is achieved, which is
520 of great importance for the future development of the electric vehicle industry.

521 Regarding the performance of the wind turbine with the VGs and the GFs placed on the blades,
522 an increment of the power of the system and the thrust force, at expenses of an increase of the bending
523 moment at the root of the WTBs, has been observed. The increased bending moment derives in higher
524 loads experienced by the structural components of the turbine.

525

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